

CABRIOLET

The invention relates to a convertible vehicle with a roof that can be stored below a cover part, whereby the cover part can alternatively be moved in
5 two different movement sequences according to the preamble of Claim 1.

A convertible vehicle is known from DE 44 45 944 C1 that provides a cover part that can be opened in two opposite movement sequences. This is held on an auxiliary frame at the rear end, which swivels around an axle
10 close to the rear end to accomplish a first movement direction and remains non-swiveled to accomplish a second movement direction while then multiple links held on the auxiliary frame open. A design of this type requires a great deal of design complications with a number of pivot points. Besides that, during release of the passage opening for a roof, the
15 cover part swivels around an axis assigned to a lock on the rear end which restricts the design options for the vehicle rear end.

DE 100 51 616 A1 shows a convertible vehicle that also provides a cover part that opens in two opposite movement sequences. For the movement of
20 the cover part to release a passage opening for the roof, a first drive is provided that comprises two levers and a gas spring and for the movement

of the cover part for releasing a loading opening for luggage, a second drive is provided that comprises a different control arm group and an associated drive. In this way, in each movement direction it is a case where one of the two gears remains completely inactive and unmoved and thus could be more simply replaced by a rigid component. Because of this, a greater design complication with a number of pivot points also results here.

The invention is based on the problem of improving a convertible vehicle of the type named at the beginning with respect to the opening mechanics of its cover part.

The invention solves this problem by a convertible vehicle with the characteristics of Claim 1. Advantageous designs of the invention can be found in the other Claims 2 to 11.

According to the invention, it is possible to achieve a case in which both opposite opening movements of the cover part can be effected with the same multi-link mechanism, whereby in each case links are used for both opening movements. Thus, no separate link arrangements are required for the opening for release of the passage opening for the roof, on one hand, and the movement for release of the loading opening for luggage, on the other. The overall design is thus considerably simplified; also the space

requirement in the vehicle and the number of pivot points is minimized. The multi-link mechanisms can be assigned in a space-saving way to the sides of the vehicle without mechanical cross connections.

- 5 If each multi-link mechanism provides just one link more than is necessary for each of the two movement sequences, the number of pivot points is kept as low as possible, which further improves the simplicity and reliability of the design.
- 10 In this case, the rear lock is also not needed as a swivel axis so the cover part can advantageously be lifted out of the lock in both movement sequences and in each case is moved with a swivel movement only by way of the multi-link chain; thus, in the area of the rear lock, no restrictions result for the rear end design.
- 15 An advantageous and simple movement kinematic results if a four-bar linkage is active for each movement direction of the cover part, i.e. in total the link chain thus comprises at least five links.
- 20 In this case, links can be of different types, say, revolute joints, prismatic joints or cam links.

In order to design the control of the individual movement sequences so that they are as simple as possible, the blocking of the redundant link necessary for the respective movement sequence can be effected mechanically in a guided way by a lock lever. This is especially
5 advantageous for reducing the number of moving parts that can be moved by a drive element which simultaneously serves to cause an opening movement of the cover part.

In addition to the normal closing position, it is advantageously possible to
10 provide a pressing position that is additionally prestressed in the closing direction for the moment of closing, say, by means of an excess pressure of the drive element, whereby an especially reliable secure closing is achieved.

15 Other advantages and characteristics of the invention will be seen from an embodiment example of the object of the invention shown in the drawing and explained in the following.

The drawings show:

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Fig. 1 a side schematic view of a rear end area of a convertible vehicle according to the invention with the cover part in closed position,

- Fig. 2 a similar view of the cover part and the associated movement mechanics as in Fig. 1 during the initial opening of the cover part to release a loading opening for luggage,
- 5 Fig. 3 a view similar to Fig. 2 with the opening of the cover part having progressed further,
- Fig. 4 a view similar to Fig. 3 with completely open cover part for releasing the loading opening for luggage,
- 10
- Fig. 5 a similar view of the rear end area as in Fig. 1 but with the start of opening of the cover part for releasing the passage opening for the roof and/or in the final phase of closing of the cover part from this movement direction with additional excess
- 15 pressure acting in the closing direction,
- Fig. 6 a similar view of the cover part and the associated movement mechanics as in Fig. 5 with opening of the cover part having progressed further to release the passage opening for the roof,
- 20
- Fig. 7 a view similar to Fig. 6 with completely opened cover

part for releasing the passage opening for the roof,

Fig. 8 a similar representation of the cover part and the movement
mechanics as in Fig. 1, but with schematic representation of the
5 active control arm and without drive and lock lever parts or
other vehicle parts that do not participate directly in the cover
part movement,

Fig. 9 a representation similar to Fig. 2, but with schematic
10 representation of the active control arm and without drive and
lock lever parts,

Fig. 10 a representation similar to Fig. 3, but with schematic
representation of the active control arms and without drive and
15 lock lever parts,

Fig. 11 Shows a representation similar to Fig. 4, but with schematic
representation of the active control arms and without drive and
lock lever parts,

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Fig. 12 a representation similar to Fig. 6, but with schematic
representation of the active control arms and without drive and
lock lever parts,

Fig. 13 Shows a representation similar to Fig. 7, but with schematic representation of the active control arms and without drive and lock lever parts.

5 Fig. 1 shows a rear end area 2 of a convertible vehicle that is designated overall with 1; this comprises a movable roof 3 that can partially, or as in this case completely, consist of rigid parts or can also be provided, outside a rear window 4, with a flexible covering. For its opening, the roof can be stored in the body 5 below a cover part 6 in a convertible top storage
10 recess.

In order to make it possible to release a passage opening for the roof 3, the cover part 6 can be swiveled in an opening movement direction in the direction of arrow 7 (Figs. 6, 7) and for closing can be swiveled back
15 opposite the arrow 7. Besides that, the cover part 6 can be opened in an opposite opening direction for releasing a loading opening for luggage in the manner of a luggage compartment lid (Fig. 2 to Fig. 4) in the direction of arrow 8 and closed opposite this direction. To make these two opening and closing movements possible, the cover part 6 is held so that it can
20 move in a moving mechanism designated overall with 9 that comprises a link chain 11. In Fig. 1, the cover part 6 is additionally held on a rear

lock 10, from which it can be released completely during each opening movement, which is not mandatory for the release 7 of the passage opening for the roof 3 but, as explained above, is advantageous. The lock 10 comprises a lock part 10a that moves along with cover part 6 and a lock
5 part 10b held on the body 5.

The moving mechanism 9 in this embodiment example comprises a bearing mount 12 on the body of which a drive element 13 and two control arms 14, 15 are held so that they can move by way of links 16, 17. The
10 entire rear lid 6 can, therefore, be installed together with its moving mechanisms 9 as a module in body 5. A separate mounting of the drive element 13 is also conceivable. The bearing mount 12 also comprises a recessed crank 18 with a first arc segment 19 that follows a large radius and runs around the swivel axis 24 of a lock lever 22 that is explained
15 further below and a second arc segment 20 that runs around the swivel axis of link 17.

In crank 18, a pin or axle journal 21 of the lock lever 22 is guided on which the drive element 13 engages on another mounting point 23 at a
20 distance from guide 21. The lock lever 22 is connected to the control arm 15 outside the guide 21 on link 24 so that it can rotate with control arm 15. In addition, the end 25 of lock lever 21 that is turned away from guide 21

is provided for an adherence-activated engagement on a latch end 27 of another control arm 26.

5 Instead of being moved by the drive element 13, which can also cause the movement of the cover part 6, lock lever 22 could be moved by its own drive, say by one that is electrically, pneumatically or hydraulically operated. Use of e.g. Piezo crystals can also be considered in order to block individual links.

10 On one hand, control arm 26 is held on lever 15 by way of link 28 and, on the other, connected on a cover-side bearing mount 29 so that it can swivel by way of link 30.

15 Between lever 15 and the cover-side bearing mount 29, or possibly another suitable control arm of the mechanism, another drive or drive-supporting element 31 extends, designed here as a gas pressure cylinder. This makes the luggage compartment opening easier.

20 Another swivel link 32 is assigned to the cover-side bearing mount 29 as a bearing point for the control arm 14 held on the other end on bearing mount 12 of body 5. This thus extends directly between body 5 and cover part 6, while in contrast the other control arm 15 supported on bearing mount 12 extends between body 5 and intermediate link 28 and the lever

26 that is connected to it extends between this intermediate link 28 and the cover part 6.

In order to open cover part 6 from the closed position (Fig. 1), in the first
5 movement direction in the direction of arrow 8 for releasing the loading
opening for luggage (Fig. 2 to Fig. 4), or then to close it opposite the
direction of arrow 8, the drive element 13 remains unmoved in its run-in
position. Because of this, lock lever 22 is also forcefully held unmoved. Its
bearing journal 21 is then forcefully held unmoved in section 19 of crank
10 18 and cannot move upward. Thus the lever 15 is prevented from a swivel
movement because of the coupling of lock lever 22 in link 24. Its body-
side link 17 is thereby blocked for this movement direction. Of the five
links 16, 17, 28, 30, 32 of the multi-link arrangement 11 with the control
arms 14, 15, 26, as well as the body-side bearing mount 12 and the cover
15 part-side bearing mount 29, thus only the four links 16, 28, 30, 32 remain
movable.

The opening can be driven by element 31 or during manual opening can
be supported by it. During the opening of the cover part 6 in the direction
20 of arrow 8, because of the blocking of link 17, only the control arms 14
swivel around link 16 in the direction of arrow 33 and control arms 26

swivel around the link 28 in the direction of arrow 34. In this process, they bring with it the bearing mount 29 connected to cover part 6 by way of links 32, 30 according to the known kinematics of four-link mechanisms.

- 5 Figures 9 to 11 schematically show the kinematics of the moving mechanism 9 again similar to Figure 2 to 4, but schematically and without the drives 13, 31 and without the lock lever 22 and its function. It is clear that for the direction of movement described, not all five links 16, 17, 28, 30, 32 are active, but only the four-link mechanism 16, 28, 30, 32 because
10 of the blocking of link 17.

In contrast, in order to move the cover part 6 from the closed position (Fig. 1) in the second movement direction in the direction of arrow 7 to release the passage opening for the roof (Fig. 5 to Fig. 7), the drive
15 element 13 drives out far enough (Fig. 5) until the pin 21 of the lock lever 22 that is moved along by the drive 13 by way of connection 23, enters into the second arc segment 20 of the crank 18. Because of this, when the piston of the drive element 13 slides out further, the bearing journal 21 in the crank 19 runs around the axis of link 17. In this way, lever 15 can be
20 swiveled because of the coupling of lock lever 22 in link 24. Because of

this, its body-side link 17 is released for this movement direction – in contrast to above.

As can be seen in the first movement phase, in which the journal 21 still
5 runs in the first, only slightly curved part 19 of the crank by the sliding out
of the drive element 13 (transition from Fig. 1 to Fig. 5), at first the swivel
movement of link 15 is still blocked. The consequence of this is that the
lock lever 22 swivels downward a little in the direction of arrow 35 around
link 24 in this phase and, with its head 25, comes in contact with a
10 recessed area 27 of control arm 26. Because of this, its swiveling in the
direction of arrow 34 around the intermediate link 28 is blocked. This
blocking is maintained during the entire movement in this opening
direction. Of the five links 16, 17, 28, 30, 32 of the multi-link arrangement
11, thus in this movement direction only the four links 16, 17, 30, 32
15 remain movable. The opening or closing can usually be caused completely
by element 13. During opening of the cover part 6 in the direction of
arrow 7, because of the blocking of link 28, only the control arm 14
swivels around the link 16 in the direction of arrow 33 and the control arm
15 around the link 17 in the direction of arrow 36. In this process, they
20 bring with them the bearing mount 29 that is tightly connected to cover
part 6 by way of link 32 and the control arm 26 that is now rigidly

connected to control arm 15 and its link 30 according to known kinematics of a four-link mechanism.

Figures 12 to 13 again show the kinematics of the moving mechanism 9
5 similarly to Figures 6 and 7, but schematically and without the drives 13, 31 and without the lock lever 22 and its function. It is clear that for the direction of movement described here from the closing position according to Fig. 8 not all five links 16, 17, 28, 30, 32 are active but, because of the blocking of link 28, only the four-link mechanism 16, 17, 30, 32 is active.
10 Therefore, in this cover part movement the control arms 15 and 26 act like a common control arm.

As above, the five-link mechanism 16, 17, 28, 30, 32 is also reduced to a four-link mechanism in this direction of movement, whereby instead of
15 the blocking of link 17 in the opening and closing directions described above, in this case link 28 is blocked.

Instead of the reduction of a five-link mechanism to a four-link mechanism, it would also be possible, for example, to block an eight-link
20 mechanism so it becomes an active seven-link mechanism or even to block several links and thus, for example, to reduce a six-link mechanism for a respective movement direction to a four-link mechanism to block at least one other link and for the opposite displacement of cover part 6.

As in the initial opening or the end phase of the closing according to Fig. 5, it becomes clear in comparison to the non-loaded and continuing closed position according to Fig. 1, that the design according to the invention also offers the possibility that the multi-link chain 11 can be moved during
5 closing of the cover part 6 while the running in of drive element 13 can be moved into a pressure-loaded downward pressed position. Because of this, an especially reliable closing of lock 10 can be achieved so that even with movement 7 in the direction of release of the passage opening for the roof, this can be lifted completely out of the lock 10 with no problems and the
10 lock axis will not be needed as the swivel axis. In the position according to Figure 5 that is run through both during opening and during closing of cover part 6, the lock lever 22 is moved downward a little around the link 24 in the direction of arrow 35 and, with its head 25, comes in contact with a recessed area 27 of control arm 26. Because of an excess dimension
15 of head 25, the control arm 26 is simultaneously pressed downward around link 28 a little further in the direction of arrow 37 and in this process pulls the cover part 6 downward with it whereby it is pressed into the lock 10, which during closing causes the reliability advantages described above.